## Proto-Quipper with dynamic lifting

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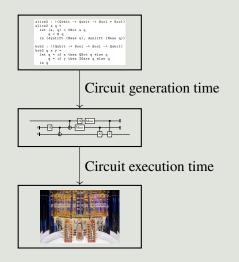
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Background and motivation

- Quipper and Proto-Quipper.
- Extend Proto-Quipper with dynamic lifting.
  - ► Categorical semantics for dynamic lifting.
  - ► Type system and operational semantics for dynamic lifting.

## Quipper/Proto-Quipper's two runtimes



Values in the two runtimes

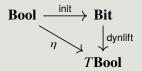
- Parameters (e.g., Nat, Bool).
- States (e.g., **Qubit**, **Bit**).
- Measurement: **Qubit**  $\rightarrow$  **Bit**.
- Dynamic lifting: an *operation* that "lifts" a **Bit** to **Bool**.
- Why dynamic lifting?

A category for the two runtimes

- Category of quantum circuits **M**.
- Category of quantum operations **Q**.
- $Kl_T(\mathbf{A})$ : Kleisli category of *T*, where *T* is commutative.

$$\begin{array}{cccc}
\mathbf{M} & & & & \\
& \downarrow_J & & \downarrow \\
\mathbf{Q} & & & & \\
\end{array}$$

A diagram for dynamic lifting



Modalities for dynamic lifting

- Modality:  $\alpha = 0 \mid 1$ .
- **Typing judgments:**  $\Gamma \vdash_{\alpha} M : A$ .
  - $\blacktriangleright \ \llbracket M \rrbracket : \llbracket \Gamma \rrbracket \to \alpha \llbracket A \rrbracket$
- **Types:**  $!_{\alpha}A$  and  $A \multimap_{\alpha} B$ .

$$\blacktriangleright \llbracket !_{\alpha} A \rrbracket = ! \alpha \llbracket A \rrbracket$$

- $\blacktriangleright \ \llbracket A \multimap_{\alpha} B \rrbracket = \llbracket A \rrbracket \multimap \alpha \llbracket B \rrbracket.$
- What is the point of these modalities?

## Type system

 $\Gamma \vdash_{\alpha} M : \mathbf{Bit}$ 

 $\Gamma \vdash_{\alpha} M : !_1(S \multimap_1 U)$  $\overline{\Gamma} \vdash_0 \mathsf{dynlift} M : \mathbf{Bool} \qquad \overline{\Gamma} \vdash_\alpha \mathsf{box}_S M : \mathbf{Circ}(S, U)$  **Operational Semantics** 

Circuit generation time: (C, M) ↓ (C', V)
 Circuit execution time: (Q, M) ↓ ∑<sub>i∈[n]</sub> p<sub>i</sub>(Q<sub>i</sub>, V<sub>i</sub>)

 $\frac{(Q, M) \Downarrow (Q', \ell) \quad \operatorname{read}(Q', \ell)}{(Q, \operatorname{dynlift} M) \Downarrow p_1(Q_1, \operatorname{True}) + p_2(Q_2, \operatorname{False})}$ 

## Main results

- A general categorical model for dynamic lifting.
- A type system and operational semantics that are sound w.r.t. the categorical model.
- Demo.